

BLIND SPOT WARNING SYSTEM

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ABSTRACT

This study introduces the use of blind spot monitoring cameras mounted on vehicles to reduce traffic accidents. At the beginning, we'll go over how intelligence surveillance, which makes use of numerous cameras, can be utilized to locate vehicle blind spots. This was accomplished using technology that detected obstacles including other cars and pedestrians as well as onlookers and other vehicles. The device initiates a countdown after a detection, which momentarily delays the alarm circuitry from activating. To lessen the possibility that a brief entry into the danger zone will trigger bothersome alerts, this waiting interval was instituted. If the obstacle's presence is still detected after the delay time, LEDs and loud alarms are triggered to warn the system operator of the potentially dangerous condition. If the obstacle's presence is still detected after the delay time, Lights and audio alerts are triggered to notify the system operator of the potentially dangerous condition. Long enough for the operator to escape the danger zone, the alarms are kept on.

KEYWORDS: BLIND SPOT, ACCIDENT, OBSTACLES, VEHICLE

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I. INTRODUCTION

When a driver collides with another car or item because they were unaware of it in their blind area, the accident is known as a blind spot accident. Even when utilizing mirrors or rotating their head, a motorist cannot see everything in the vicinity of their car because of blind spots. Accidents caused by these blind areas happen frequently, especially on roads and motorways where cars are moving quickly.

A blind spot detecting system for defence against accidents, impediments, and mishaps like car crashes that cause significant loss of human life and can have catastrophic outcomes.

The blind spot accident prevention system (BSAPS) is designed to avoid accidents by detecting blind spots in front of moving vehicles and to improve traffic safety. Some of these systems will launch on the market sooner than others. Adding to the current Cameras and sensors

are used to implement BSAPS. Also, there is a dearth of knowledge on users' readiness to adopt and pay for new technology. The regions towards the rear of the car on both sides that are most frequently referred to be blind spots are the rear quarter blind spots. vehicles on the road's adjacent lanes, which are likely to have a good influence.

II. VEHICLE BLIND SPOT

Radio waves were sent and received at the sensor's receiving end during the first stage of BSAPS. when a thing is found. The circuit is activated in the second step by the radio waves that were picked up at the receiver's end. The circuit's output can be shown as both auditory alerts and LEDs that are lighting.

A proximity sensing system like this oneradio frequency waves are used. It consists of five components: a front sensor, a side sensor on each side, a

side sensor on the right, an LED meter, and an Auditory alarm.

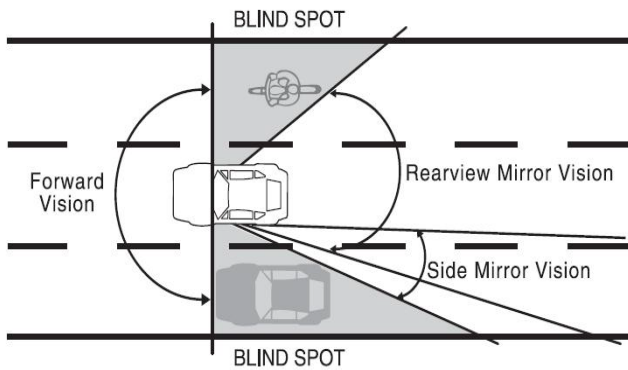


Fig: 01

The front sensor is mostly useful for identifying seasonal black areas (such as front-light failure in cases of fog). By transmitting radio waves, this sensor can identify the presence of any object and, in the event of momentary blind areas, can alert the user to impending threats.

Fundamentally, a metal strip covering the whole back region of the car extends from left to right. Depending on the kind of vehicle, we use a left side sensor at the far left and a right-side sensor at the far right of that strip.

This display meter really has LEDs that light up when a nearby creature is detected, signaling a potential concern. After Clearing, these LEDs will no longer be illuminated. The front will have this LED meter fitted. As it is observed that the LEDs on the left hand side are lighting, indicating the presence of an obstruction or a creature, the left side sensor detects a blind spot. As shown in fig 01.

As it is observed that the LEDs on the top (front) side are lighting, indicating the presence of an object or a creature, the front sensor detects a brief blind area. The delay one-shot 8 starts a predefined scheduled delay period before the alarm is activated when the output of the ultrasonic detecting circuit becomes engaged. The delay is chosen to prevent nuisance alarms from being set off by detecting circuit responses that are of a transient character (produced, for instance, by a bird passing across the danger zone). The alarms stay silent and system function is unaffected if the hazard zone is removed, making the detection circuit 6 inactive, before the delay one-shot 8 times out.

III. AUDIBLE ALARM

An audio alarm is generated to communicate the detection of an entity as soon as the detection of an entity is verified and LED begin to illuminate on the

LED meter. When an LED or display malfunctions, this loud alert is quite helpful.

The sensor that is used in this part was installed as seen in the image below.

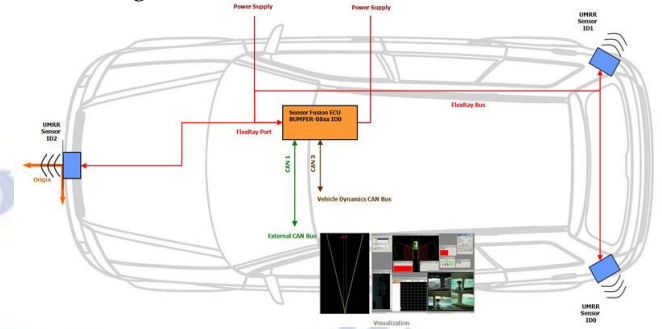


Fig: 02

In the example shown in Figure, a pair of ultrasonic transducers—transmitter 2 and receiver 4—are utilized as the sensors. Sensor signal transmission is controlled by an ultrasonic detecting circuit 6 or other detection device linked to the sensor means, which also checks sensor output signals at the receiver 4. Aberrations in the received sensor signal will be interpreted by the ultrasonic circuit 6 as an incursion, activating the output of the detecting circuit that is to be asserted. as shown in fig 02.

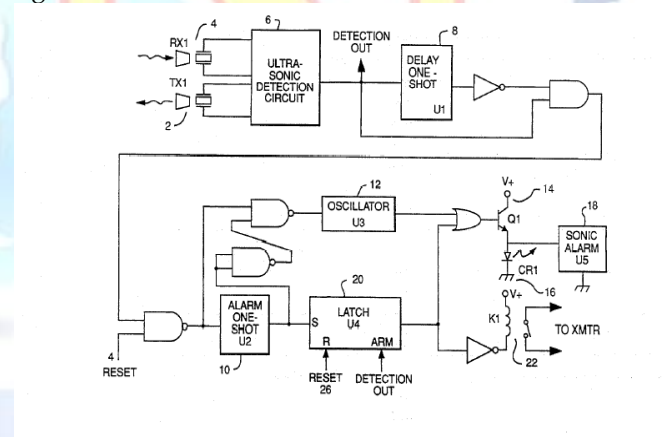


Fig:03

The delay one-shot 8 starts a delay cycle when the ultrasonic detecting circuit's active output does. Prior to the alarm going off, there is a timed wait. The delay is chosen to prevent nuisance alarms from being set off by detecting circuit responses that are of a transient character (produced, for instance, by a bird passing across the danger zone). The alarms stay silent and system function continues without interruption if the hazard zone is removed, making the detection circuit 6 inactive, before the delay one-shot 8 times out.

Now a description of the system circuit block diagram follows. To identify a presence in the RFR zone, the gadget includes detection circuitry that uses one or

more sensor techniques. Ultrasonic, passive, infrared (IR), active, or other sensors may be used by the detecting circuit as sensor methods, either singly or in combination. As shown in fig 03.

ALSO, THE SEQUENCE DESCRIBED FOR PULSING THE ALARMS,

The desired procedure is to provide continual alarms and switch off the transmitter, while other sequences are being considered. For instance, when the latch 20 has been activated, an ongoing alert may be sent until the delay one-shot 8 expires. The oscillator 12 may now be activated and the latch 20 disengaged, resulting in a pulsating alarm. The specific order involved is not essential to the current innovation.

On the latch 20, a reset button 26 or other reset method is available for deactivating the alarms and the transmitter shutdown relay. The RF transmitter will be activated when the reset button 26 is depressed so long as the detecting circuit 6's output signal is no longer asserted. To verify the functionality of the device while the transmitter is turned off, a circuit test button 24 or other test methods are also available. Pushing the circuit test button 24 will ideally activate the alarm LED and loud alert and deactivate the RF transmitter in the order that is followed during normal operation.

IV. BLIND SPOT ACCIDENT PREVENTION SYSTEM

The current invention pertains to the blind spot detection of a radio frequency transmitter and, more specifically, to a proximity detection device for identifying the presence of a person inside its radio frequency zone. When one is present in the radio frequency zone, the gadget sets out an audio alert and flashes LEDs to indicate that it is there. Alarms and LEDs are activated once objects (obstacles) have been removed from the radio frequency zone.

V. OUTCOMES AND GOAL OF THE RESEARCH

The function of blind-spot monitoring is quite self-explanatory. It keeps an eye on your blind areas and warns you if you attempt an improper lane change that can lead to a collision with another car. To assist prevent an accident, this is frequently done with both visible and aural notifications using lights and sounds. To avoid a collision to implement new mechanisms to prevent accidents

VI. ENFORCEMENT

Blind spot detection is one of the smart technologies that has seen a spike in use in the automobile sector. Sensor-based safety technology known as blind spot detection (BSD) identifies people and obstructions in the area surrounding moving vehicles. Passengers seated inside the car are to blame for the blind spot.

VII. ADVANTAGES OF BLIND SPOT SYSTEM

One of the main benefits of blind spot detection systems is that they can:

- Increased level of safety
- Reduction in truckload and auto body damage
- Give accurate information on vehicles in the blind spot.
- Safe lane changes in both the city and on the highway.
- Reduces the risk of collisions by warning of impending ones with cars in the blind spot.
- Prevents accidents resulting from incorrect estimation of the speed of oncoming vehicles
- Instantly displays a warning when it detects a vehicle in the vehicle's blind zone.

VIII. CONCLUSION

This BSAPS uses sensors to identify blind spots inside its field of view and to signal the presence of objects (automobiles). Once the identification is made, LEDs and an auditory alert are activated. The LEDs and loud alerts go off once a creature leaves the area, signaling to the driver to comfortably move to the right or left.

As a result, this technology will significantly contribute to raising road safety and lowering accidents and mishapenness.

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